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THE AMERICAN SOCIETY OF MECHANICAL ENGINEERS  
29 West 39th Street, New York 18, N. Y.

## Stability of Honeycomb Sandwich Cylinders

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This paper treats the instability of a honeycomb-sandwich cylinder under axial compression, torsion, and external lateral pressure. The simply supported honeycomb-sandwich cylinder considered here has face sheets of equal thickness and an isotropic honeycomb core. Curves are presented for the cases of axial compression and lateral pressure only, as well as torsion only. The combined case is handled by means of interaction equations based on the curves shown.

19960424 028

DEPARTMENT OF DEFENSE  
PLASTICS TECHNICAL EVALUATION CENTER  
PICATINNY ARSENAL, DOVER, N. J.

For presentation at the Aviation Conference, Los Angeles, Calif., March 12-16, 1961  
of The American Society of Mechanical Engineers. Manuscript received at ASME  
Headquarters, January 9, 1961.

Written discussion on this paper will be accepted up to April 17, 1961.

Copies will be available until January 1, 1962.

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# Stability of Honeycomb Sandwich Cylinders

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## NOMENCLATURE

$b$  = circumferential dimension ( $= 2\pi R$ )

$t_f$  = core thickness

$D$  = flexural rigidity of panel

$$\left( = \frac{E_f I}{1-\nu^2} \right)$$

$E_f$  = Young's Modulus for the face sheet

$\bar{\sigma}$  = actual stress

$F$  = allowable stress

$G_c$  = core shear modulus

$J$  = a parameter representing ratio of shear to flexural stiffness

$$\left( = \frac{L^2 u}{\pi^2 D} \right)$$

$K$  = buckling coefficient  $\left( = N \frac{L^2}{\pi^2 D} \right)$

$L$  = length of cylinder

$m, n$  = integers (1, 2, 3, and so on)

$N$  = load (lb/in.)

$p$  = external lateral pressure load (psi)

$R$  = radius of cylinder to mid-point of face sheets or ratio of actual stress to theoretical critical stress

$t_F$  = face sheet thickness

$u, v, w$  = displacement of point on shell median surface in X, Y, and Z-directions respectively

$U$  = shear rigidity of panel  $\left[ = G_c'(C+2t_F) \right]$

$X$  = axial co-ordinate of panel

$Y$  = circumferential co-ordinate of panel

$Z$  = radial co-ordinate of panel

$$Z_1^2 = \frac{2Et_f}{R^2} \frac{L^4}{\pi^4 D}$$

$$\beta = \frac{\pi L}{b}$$

$\eta$  = plasticity correction

$\mu$  = Poisson's ratio ( $= 0.3$  for calculations)

$$\lambda = N_{xy}/N_x$$

$$\lambda' = N_y/N_x$$

$$\lambda'' = 1/\lambda'$$

$$\theta = b/R$$

$$\theta_{bK} = \theta \cdot \frac{b}{C+t_F} \cdot \left( \frac{L}{b} \right)^2 = \frac{L^2}{R(C+t_F)}$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

$$\nabla^4 = \frac{\partial^4}{\partial x^4} + \frac{2}{\partial x^2 \partial y^2} + \frac{\partial^4}{\partial y^4}$$

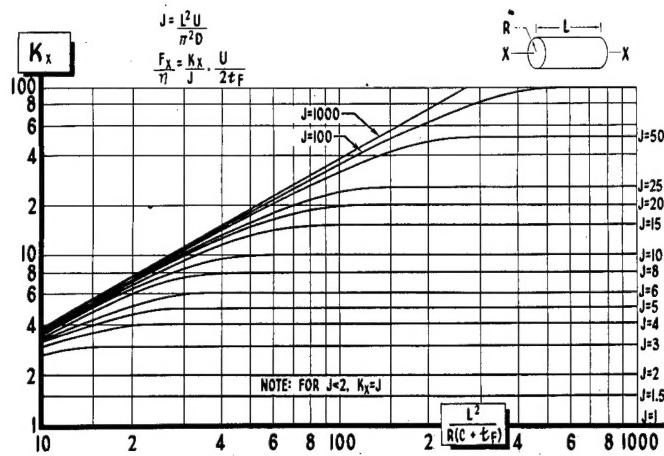


Fig. 1 Buckling of S S sandwich cylinder loaded in axial compression

$$\nabla^{-4} = \text{inverse of } \nabla^4$$

## Subscripts

s = shear

x = in x-direction

y = in y-direction

xy = in xy-direction (torsion)

## INTRODUCTION

For the case of thin-walled cylinders, the critical combination of torsion and axial load has been treated previously (3),<sup>1</sup> as has been the combination of torsion and external lateral pressure (10). Theoretical equations for sandwich cylinders under axial compression only (12), torsion only (6), and lateral pressure only (7) have also been treated. Therefore, the scope of this paper is to extend the presently known formulas to the case studied, and to present the results in the form of easily used graphs.

## DISCUSSION

The mathematical derivations of the equations, as well as the assumptions, are presented in the Appendix.

The critical combination of loads that causes the general instability failure of a simply supported, isotropic honeycomb sandwich cylinder under axial compression, external lateral pressure, and torsion can be obtained from the equations

<sup>1</sup> Underlined numbers in parentheses designate References at the end of the paper.

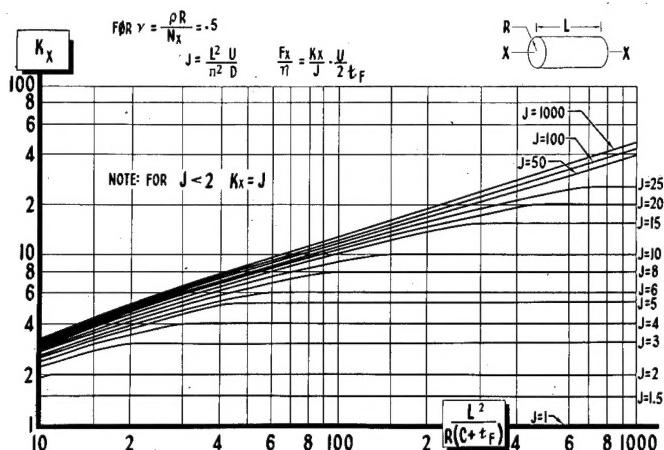


Fig. 2 Buckling of S S sandwich cylinder loaded in axial compression and lateral pressure

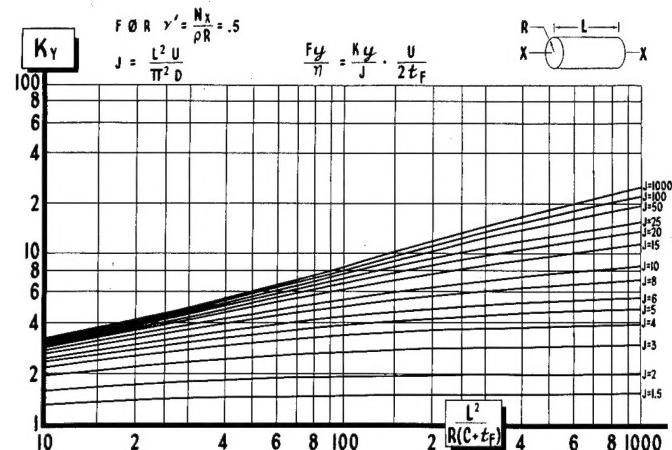


Fig. 4 Buckling of S S sandwich cylinder loaded in axial compression and lateral pressure

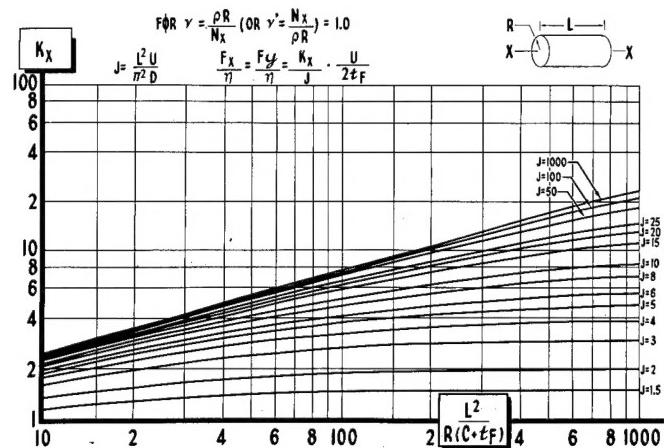


Fig. 3 Buckling of S S sandwich cylinder loaded in axial compression and lateral pressure

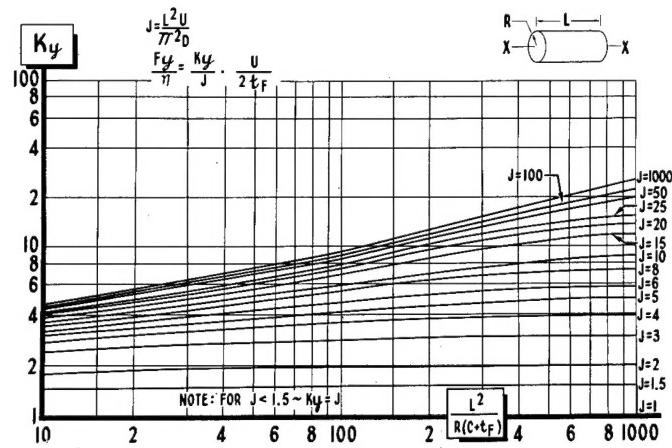


Fig. 5 Buckling of S S sandwich cylinder loaded in lateral pressure

$$\frac{F_x}{\eta} = \frac{K_x^1 \pi^2 D}{2L^2 t_F} \text{ or } \frac{K_x^1}{J} \cdot \frac{U}{2t_F} \quad (1)$$

or

$$\frac{F_y}{\eta} = \frac{K_y^1}{J} \cdot \frac{U}{2t_F} \quad (2)$$

and

$$\frac{F_s}{\eta} = \frac{K_{xy}^1}{J} \cdot \frac{U}{2t_F} \quad (3)$$

when the stress coefficients  $K_x^1$  or  $K_y^1$  and  $K_{xy}^1$  are known. The curves required to obtain these coefficients are shown in Figs. 1 through 11. The equations used to obtain the curves are equations (A12) and (A13) (Appendix). Since the radius of

the cylinder is assumed to be large compared to the thickness of the sandwich,  $N_y = pR$ .

When a cylinder is loaded under axial compression only, axial compression and lateral pressure only, lateral pressure only, or torsion only, Figs. 1, 2 through 4, 5, or 6, respectively, can be used to calculate  $K_x^1$ ,  $K_y^1$ , or  $K_{xy}^1$ . However, when the combined case is required, use of the interaction curves, Figs. 7 through 11, will be required. The use of these curves is as follows:

1 Find  $K_x^1$  or  $K_y^1$  and  $K_{xy}^1$  for the uncombined cases, Figs. 1 through 6.

2 Calculate  $R_x^1/R_y^1 = (f_x/f_s)(K_{xy}^1/K_x^1)$  or  $R_y^1/R_{xy}^1 = (f_y/f_s)(K_{xy}^1/K_y^1)$

3 Using the appropriate interaction curve, Figs. 7 through 11,  $K_x^1$  or  $K_y^1$  and  $K_{xy}^1$  can now be

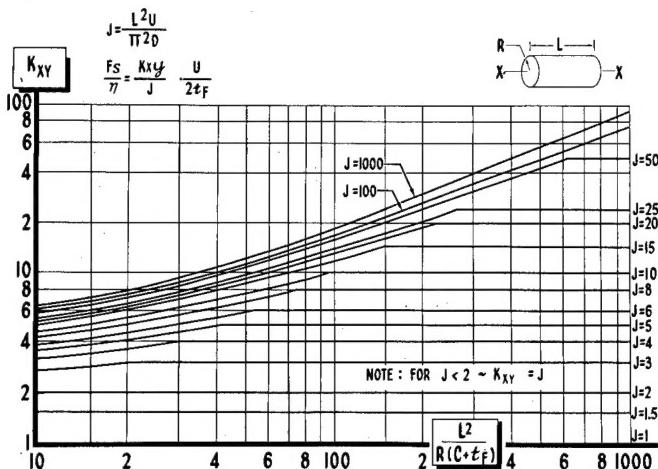


Fig. 6 Buckling of S S sandwich cylinder loaded in torsion

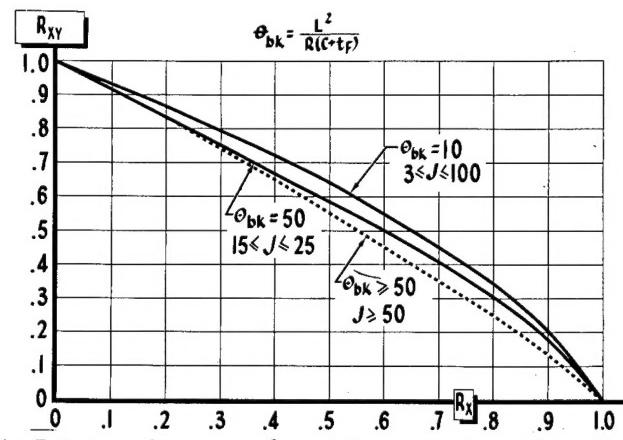


Fig. 7 Interaction curves for axial compression and torsion

found from the relationships  $K_x = R_x K_x$  or  $K_y = R_y K_y$ , and  $K_{xy} = R_{xy} K_{xy}$ .  $F_x$  or  $F_y$  and  $F_{xy}$  can now be obtained from equation (1) or (2) and equation (3).

In order to facilitate further the calculations,  $J$  can be obtained from Fig. 12.

In order to obtain the curves, Figs. 1 through 11, equations (A12) and (A13) (Appendix) were solved for various  $J$ ,  $\theta_{bk}$ ,  $\beta'$ , and  $R_x$  or  $R_y$ . This was done by means of the IBM 7090 high-speed digital computer. Since it was impossible to plot all the interaction curves which resulted, the curves shown represent typical results and will produce a maximum of a 5 per cent error from the theoretical in the range given. This is well within engineering accuracy for a problem of this type. When  $J$  and  $\theta_{bk}$  are chosen so that  $K_{xy} = J$ , then the interaction equation  $R_x^2 + R_{xy}^2 = 1$  should be used. It should also be noted that when  $L/R > 10$ , the values obtained

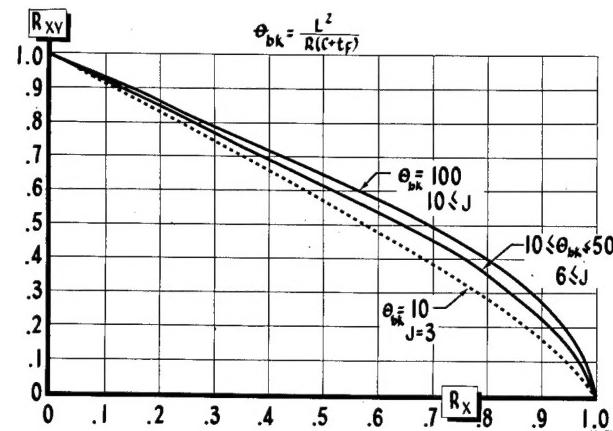


Fig. 8 Interaction curves for axial compression and ex-  
ternal lateral pressure and torsion for  $v = 1/2$

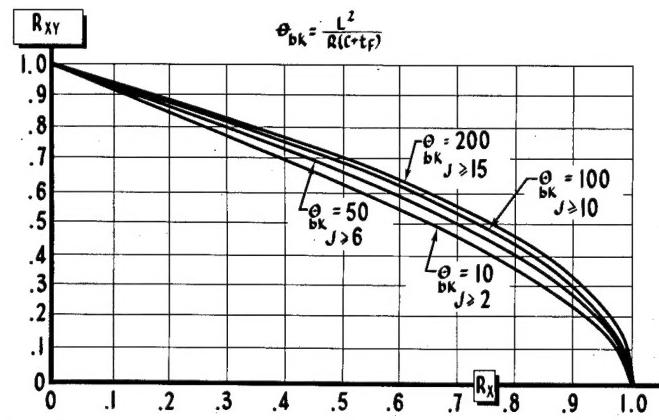


Fig. 9 Interaction curves for axial compression and lateral  
external pressure and torsion for  $v = 1$

from the curves will be conservative, since  $n$  in equation (A13) must be an integer.

It has previously been observed that test results for axially loaded, thin-walled cylinders did not agree with the theoretical values obtained from the small-deflection theory. However, because of the increased thickness inherent in honeycomb-sandwich construction, this problem should not be encountered. Test results are available for axial compression only (11, 12), and torsion only (11). The tests for axial compression were in the region of  $K_x = J$ , and there is reasonably good agreement with theory. The torsion tests were inconclusive.

According to (12)  $K_x = J$  for  $\beta' = 0$  when  $\theta_{bk} \geq 5.18 J$ , and  $K_x = J$  when  $\theta_{bk} \geq 10.36 J$ . The curves for Figs. 1 ( $\beta' = 0$ ) and 6 seem to verify these relationships. However, there is a slight difference in the case where  $K_x = J$ , since an insufficient number of terms of the ma-

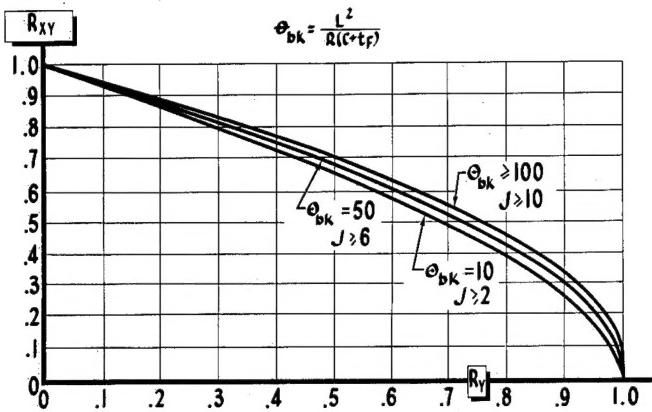


Fig. 10 Interaction curves for axial compression and external pressure and tension for  $\nu' 1/2$

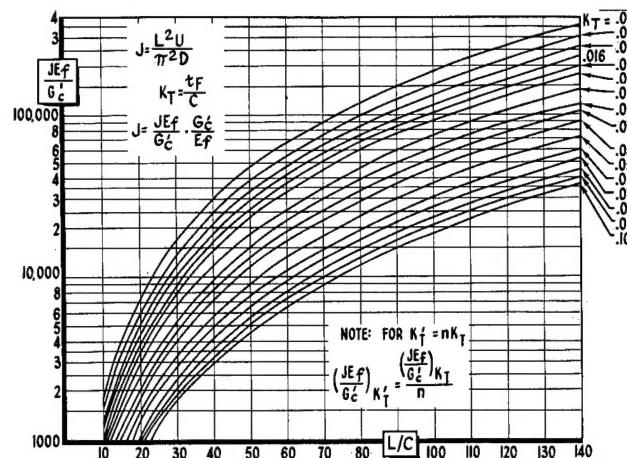


Fig. 12 Determination of J

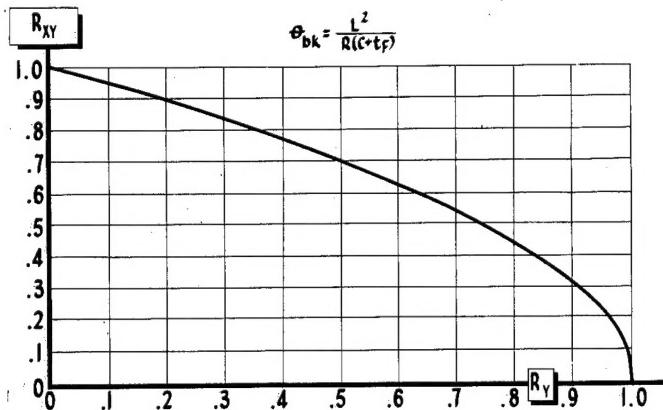


Fig. 11 Interaction curve for external lateral pressure and torsion  $\nu' = 0$

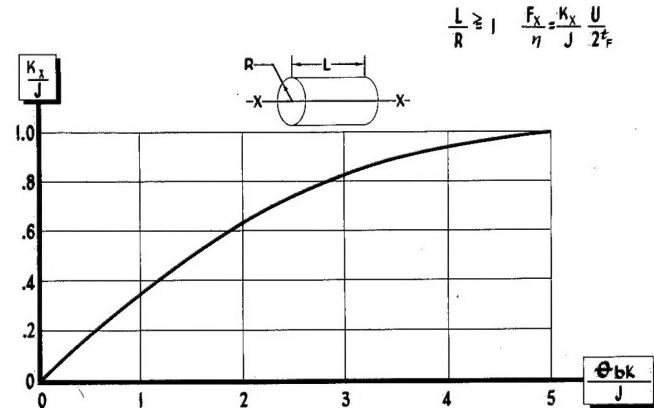


Fig. 13 Compression buckling of simply supported sandwich cylinders loaded in the axial direction only

trix, equation (A12) were taken. The curves for  $\nu' = 0$ , Fig. 1, can be replaced by the single curve in Fig. 13, by changing the parameters to those shown.

#### CONCLUSION

A theoretical solution for the general instability of a simply supported, isotropic honeycomb sandwich cylinder under axial compression, external lateral pressure, and torsion is presented in the Appendix.

The resulting curves were drawn and shown in Figs. 1 through 11. The use of these curves should produce an error of less than  $\pm 5$  per cent from the theoretical equations.

The very limited test results available showed reasonably good agreement with the theory.

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## APPENDIX A

### THEORETICAL SOLUTION FOR A SANDWICH CYLINDER

The following assumptions were made to derive the equations in this appendix:

1. Face plates are of identical material and thicknesses.
2. Core is isotropic.
3. Core does not carry any bending stresses.
4. Face sheets do not carry any normal shear stresses.
5. Radius of the cylinder or curved plate is large compared to the thickness of the sandwich.
6. Axial compression is uniform.
7. Lateral external pressure produces uniform compression constant throughout the perimeter.
8. Radial deflection of the cylinder before buckling is small compared to the sandwich thickness.

The equation of equilibrium for a honeycomb sandwich cylinder in terms of the transverse deflections of the median surface was formulated by Wang and De Santo (Reference 12). This modified form of Donnell's equation is shown below.

$$Q_1(w) = 0 \quad (A1)$$

Where  $(Q_1)$  is the operator defined by

$$Q_1 = \nabla^4 + \left(\frac{1}{D} - \frac{\nabla^2}{R^2}\right) \left[ \nabla^{-4} \frac{1}{R^2} \frac{\partial^4}{\partial x^4} - \left( N_x \frac{\partial^2}{\partial x^2} + N_y \frac{\partial^2}{\partial y^2} + 2N_{xy} \frac{\partial^2}{\partial x \partial y} \right) \right] \quad (A2)$$

Here the implied boundary conditions are

$$w(0,y) = w(L,y) = \frac{\partial^2 w}{\partial x^2}(0,y) = \frac{\partial^2 w}{\partial x^2}(L,y) = 0 \quad (A3)$$

Using the Galerkin method and defining  $w$  as shown below in order to

satisfy the boundary conditions

$$w = \sin \frac{n\pi y}{b} \sum_{m=1}^{\infty} a_m \sin \frac{m\pi x}{L} + \cos \frac{n\pi y}{b} \sum_{m=1}^{\infty} b_m \sin \frac{m\pi x}{L} \quad (A4)$$

Following Galerkin's method, two sets of n simultaneous equations are obtained.

$$\iint V_p Q(w) dx dy = 0 \quad (A5a)$$

$$\iint W_p Q(w) dx dy = 0 \quad \text{where} \quad (A5b)$$

$$V_p = \sin \frac{n\pi y}{b} \sin \frac{p\pi x}{L} \quad (A6a)$$

$$W_p = \cos \frac{n\pi y}{b} \sin \frac{p\pi x}{L} \quad (A6b)$$

Letting  $Q = Q_1$  and substituting equations A2, A4, and A6a into equation

A5a, we obtain

$$0 = \iint \sin \frac{n\pi y}{b} \sin \frac{p\pi x}{L} \left\{ \left[ \nabla^4 \left( \frac{1}{D} - \frac{\nabla^2}{R^2} \right) \left[ \nabla^4 \frac{2Etf}{R^2} \frac{\partial^4}{\partial x^4} - \left( N_x \frac{\partial^2}{\partial x^2} + N_y \frac{\partial^2}{\partial y^2} + 2N_{xy} \frac{\partial^2}{\partial x \partial y} \right) \right] \right] \right. \\ \left. \left[ \sin \frac{n\pi y}{b} \sum_{m=1}^{\infty} a_m \sin \frac{m\pi x}{L} + \cos \frac{n\pi y}{b} \sum_{m=1}^{\infty} b_m \sin \frac{m\pi x}{L} \right] \right\} dx dy \quad (A7)$$

Also letting  $Q = Q_1$  and substituting equations A2, A4, and A6b into equation

A5b, we obtain the second set of equations.

$$0 = \iint \cos \frac{n\pi y}{b} \sin \frac{p\pi x}{L} \left\{ \left[ \nabla^4 \left( \frac{1}{D} - \frac{\nabla^2}{R^2} \right) \left[ \nabla^4 \frac{2Etf}{R^2} \frac{\partial^4}{\partial x^4} - \left( N_x \frac{\partial^2}{\partial x^2} + N_y \frac{\partial^2}{\partial y^2} + 2N_{xy} \frac{\partial^2}{\partial x \partial y} \right) \right] \right] \right. \\ \left. \left[ \sin \frac{n\pi y}{b} \sum_{m=1}^{\infty} a_m \sin \frac{m\pi x}{L} + \cos \frac{n\pi y}{b} \sum_{m=1}^{\infty} b_m \sin \frac{m\pi x}{L} \right] \right\} dx dy \quad (A8)$$

Performing the integration over the limits gives,

$$a_m \left[ \left( m^2 + \beta^2 \right)^2 + \frac{m^4 z_i^2}{\left( m^2 + \beta^2 \right)^2} \left[ 1 + \frac{m^2 + \beta^2}{J} \right] + K_X \left( m^2 + \gamma \beta^2 \right) \left[ 1 + \frac{m^2 + \beta^2}{J} \right] \right] - 8K_{xy} \frac{\beta}{\pi} \sum_{p=1}^{\infty} b_p \frac{m p}{\beta^2 p^2} \left[ 1 + \frac{p^2 + \beta^2}{J} \right] = 0 \quad (A9a)$$

$$b_m \left[ \left( m^2 + \beta^2 \right)^2 + \frac{m^4 z_i^2}{\left( m^2 + \beta^2 \right)^2} \left[ 1 + \frac{m^2 + \beta^2}{J} \right] + K_X \left( m^2 + \gamma \beta^2 \right) \left[ 1 + \frac{m^2 + \beta^2}{J} \right] \right] + 8K_{xy} \frac{\beta}{\pi} \sum_{p=1}^{\infty} a_p \frac{m p}{\beta^2 p^2} \left[ 1 + \frac{p^2 + \beta^2}{J} \right] = 0 \quad (A9b)$$

Where:

tension is (+),  $m+p = \text{odd}$  integers,

$$N_{xy} = K_{xy} \frac{\pi^2 D}{L^2} \text{ and, } N_x = K_x \frac{\pi^2 D}{L^2}$$

It is possible to obtain a nontrivial solution for equations A9 and A10

by setting their determinant equal to zero

	$a_1$	$b_2$	$a_3$	$b_4$	$a_5$	$b_6$	
$m=1$	$\frac{M_1}{K_{xy}}$	$\frac{2}{3}(1+\frac{i^2+\beta^2}{J})$	0	$\frac{4}{15}(1+\frac{i^2+\beta^2}{J})$	0	$\frac{16}{35}(1+\frac{i^2+\beta^2}{J})$	...
$m=2$	$\frac{2}{3}(1+\frac{i^2+\beta^2}{J})$	$\frac{M_2}{K_{xy}}$	$-\frac{6}{5}(1+\frac{i^2+\beta^2}{J})$	0	$-\frac{10}{21}(1+\frac{i^2+\beta^2}{J})$	0	...
$m=3$	0	$-\frac{6}{5}(1+\frac{i^2+\beta^2}{J})$	$\frac{M_3}{K_{xy}}$	$\frac{12}{7}(1+\frac{i^2+\beta^2}{J})$	0	$\frac{2}{3}(1+\frac{i^2+\beta^2}{J})$	0
$m=4$	$\frac{4}{15}(1+\frac{i^2+\beta^2}{J})$	0	$\frac{12}{7}(1+\frac{i^2+\beta^2}{J})$	$\frac{M_4}{K_{xy}}$	$-\frac{20}{9}(1+\frac{i^2+\beta^2}{J})$	0	...
$m=5$	0	$-\frac{10}{21}(1+\frac{i^2+\beta^2}{J})$	0	$-\frac{20}{9}(1+\frac{i^2+\beta^2}{J})$	$\frac{M_5}{K_{xy}}$	$\frac{30}{11}(1+\frac{i^2+\beta^2}{J})$	...
$m=6$	$\frac{6}{35}(1+\frac{i^2+\beta^2}{J})$	0	$\frac{2}{3}(1+\frac{i^2+\beta^2}{J})$	0	$\frac{30}{11}(1+\frac{i^2+\beta^2}{J})$	$\frac{M_6}{K_{xy}}$	...
	⋮	⋮	⋮	⋮	⋮	⋮	⋮

(A 10)

$$\text{Here } M_i = \frac{\pi}{8\beta} \left[ (\zeta^2 + \beta^2)^2 + \frac{4\zeta^2}{(\zeta^2 + \beta^2)^2} (1 + \frac{\zeta^2 + \beta^2}{J}) + K_x (\zeta^2 + \gamma\beta^2) (1 + \frac{\zeta^2 + \beta^2}{J}) \right] \quad (A 11)$$

Factoring each column with the proper  $(1 + \frac{i^2 + \beta^2}{J})$  and calling  
 $N_i = \frac{M_i}{(1 + \frac{i^2 + \beta^2}{J})}$

We obtain the following determinant:

	$a_1$	$b_2$	$a_3$	$b_4$	$a_5$	$b_6$	
$m=1$	$\frac{N_1}{K_{xy}}$	$\frac{2}{3}$	0	$\frac{4}{15}$	0	$\frac{6}{35}$	...
$m=2$	$\frac{2}{3}$	$\frac{N_2}{K_{xy}}$	$-\frac{6}{5}$	0	$-\frac{10}{21}$	0	...
$m=3$	0	$-\frac{6}{5}$	$\frac{N_3}{K_{xy}}$	$\frac{12}{7}$	0	$\frac{2}{3}$	...
$m=4$	$\frac{4}{15}$	0	$\frac{12}{7}$	$\frac{N_4}{K_{xy}}$	$-\frac{20}{9}$	0	...
$m=5$	0	$-\frac{10}{21}$	0	$-\frac{20}{9}$	$\frac{N_5}{K_{xy}}$	$\frac{30}{11}$	...
$m=6$	$\frac{6}{35}$	0	$\frac{2}{3}$	0	$\frac{30}{11}$	$\frac{N_6}{K_{xy}}$	...
	⋮	⋮	⋮	⋮	⋮	⋮	⋮

(A 12)

$$\text{Here } N_i = \frac{\pi}{8\beta} \left[ \frac{(i^2 + \beta^2)^2}{(1 + \frac{i^2 + \beta^2}{J})} + \frac{\frac{4(1-\mu^2)}{\pi^4} \Theta_{bK}^2 i^4}{(i^2 + \beta^2)^2} + K_x(i^2 + \gamma\beta^2) \right] \quad (A13)$$

$$\text{Where } \Theta_{bK} = \frac{L^2}{R(c+t_f)} \quad (A14)$$

Using a third-order determinant and solving for  $K_{xy}$  we obtain

$$K_{xy} = \sqrt{\frac{N_1 N_2 N_3}{(\frac{6}{5})^2 N_1 + (\frac{2}{3})^2 N_3}} \quad (A15)$$

Knowing  $K_x, \gamma, \Theta_{bK}$  we can plot  $K_{xy}$  against  $\beta$  and find the minimum value of  $K_{xy}$ .

A better approximation can be obtained from the fourth order determinant

$$K_{xy}^2 = \frac{(\frac{12}{7})^2 N_1 N_2 + (\frac{6}{5})^2 N_1 N_4 + (\frac{4}{15})^2 N_2 N_3 + (\frac{2}{3})^2 N_3 N_4 - \sqrt{[(\frac{12}{7})^2 N_1 N_2 + (\frac{6}{5})^2 N_1 N_4 + (\frac{4}{15})^2 N_2 N_3 + (\frac{2}{3})^2 N_3 N_4]^2 - 4 N_1 N_2 N_3 N_4 (\frac{6}{7} + \frac{6}{25})^2}}{2(\frac{6}{7} + \frac{6}{25})^2} \quad (A16)$$

### PARTICULAR CASES

Case I - axial compression only

Let  $N_i$  and  $\gamma$  (in equation A13) = 0

$$K_x = (-)$$

$$\text{Then } K_x = \frac{(i^2 + \beta^2)^2}{i^2(1 + \frac{i^2 + \beta^2}{J})} + \frac{4(1-\mu^2)\Theta_{bK}^2 i^2}{\pi^4 (i^2 + \beta^2)^2}$$

Case II - Axial compression + lateral pressure

Let  $N_i$  (in equation A13) = 0

$$K_x = (-)$$

$$\text{Then } K_x = \frac{(i^2 + \beta^2)^2}{(1 + \frac{i^2 + \beta^2}{J})(i^2 + \gamma\beta^2)} + \frac{4(1-\mu^2)\Theta_{bK}^2 i^4}{\pi^4 (i^2 + \beta^2)^2 (i^2 + \gamma\beta^2)}$$

Case III - Lateral pressure only

$$\text{Let } K_x(i^2 + \gamma\beta^2) = -K_y\beta^2 \text{ (in equation A13)}$$

and let  $N_i \approx 0$

$$\text{Then } K_y = \frac{(i^2 + \beta^2)^2}{\beta^2(1 + \frac{i^2 + \beta^2}{J})} + \frac{4(1-\mu^2)\Theta_{bK}^2 i^4}{\pi^4 \beta^2 (i^2 + \beta^2)^2}$$

Case IV - Torsion only

$$\text{Let } K_x \text{ (in equation A13)} = 0$$

$$\text{Then } N_i = \frac{\pi}{8\beta} \left[ \frac{(i^2 + \beta^2)^2}{(1 + \frac{i^2 + \beta^2}{J})} + \frac{4(1-\mu^2)\Theta_{bK}^2 i^4}{\pi^4 (i^2 + \beta^2)^2} \right]$$

Case V - Small deflection theory equation for a thin-walled cylinder

Let  $J \rightarrow \infty$  and  $\theta_{bk}^2 = \frac{3L^4}{R^2 t^2}$

in equation A13 and cases I, II, III, and IV